

1st CARES Stakeholder Advisory Board Meeting

10:00	Welcome & introduction, incl. tour-de-table	Ake Sjodin, IVL Harald Jenk, BAFU
10:15	CARES project overview & objectives	Peter Mock, ICCT
10:30	Current status of hardware developments - plume chasing and point sampling	David Carslaw, University of York
10:55	Standardizing remote sensing data management processes	James Tate, University of Leeds
11:20	Five minutes break	
11:25	Using remote sensing for monitoring and enforcement purposes	Jens Borken-Kleefeld, IIASA
11:50	Wrap up & next steps	Ake Sjodin, IVL
12:00	End of meeting	



Meeting participants – tour-de-table

Stakeholder Advisory Board

CITA/Bilprovningen, SE
CITA/GOCA, BE
City of Krakow, PL
City of Prague, SZ
EPHA
European Commission
Federal Office of Environment, CH
Fia Foundation
Government of Flanders, BE
Hong Kong EPD, CN
Ministry of Transport, SZ
Ministry of Transport, IT
Transport Scotland, UK
VECC, CN

CARES Partners

Airyx, DE
City of Milan, IT
Czech Technical University, CZ
ICCT, DE
IIASA, AT
Innovhub, IT
IVL Swedish Environmental Research Institute
Krakow Smog Alert, PL
Technical University Graz, AT
TNO, NL
Tsinghua University, CN
University of Leeds, UK
University of York, UK



ReMOVES - (Remote Monitoring of Onroad Vehicle Emissions in Switzerland)

- Research project of the Federal Road Office
- Consortium: EMPA, AFHB, Innet (HEAT, OPUS) ICCT/Jens Borken
- Goal: test RSD as a tool for detecting NOx high emitters in Switzerland (market surveillance, tuning, Adblue-emulators), cars and HDVs
- Data: measurement campaigns with OPUS and EDAR/HEAT in 2021, with a focus on highways
- Start: spring 2020, end: 2022



The CARES project

An overview of the objectives and possibilities
for engagement of member states and stakeholders

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Dr. Peter Mock, International Council on Clean Transportation (ICCT)

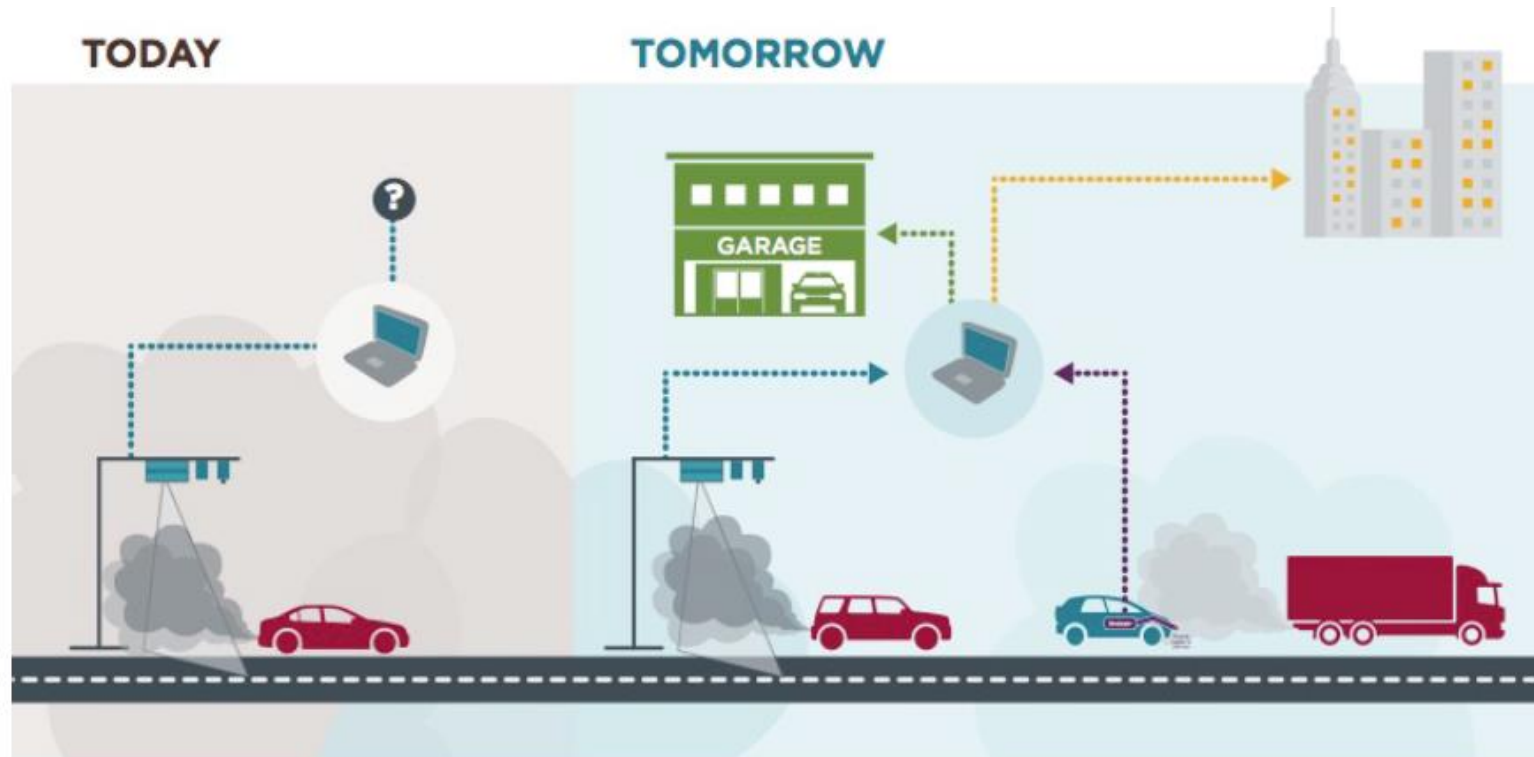
Web-meeting – May 28, 2019



What is CARES?

Working towards a joint project goal

“Reduce the hurdles for practical applications of remote emission sensing and to make it a widespread means of both, monitoring as well as enforcing, improvements in road vehicle emissions.”



What is CARES?

Responding to the Horizon 2020 Work Programme

- [...] **further technological development of available techniques** is needed to improve performance, reduce costs, facilitate use by unskilled personnel and achieve a broader deployment potential;
- Establishment of a **proper data infrastructure** built around vehicle registration databases, traffic management measures and air quality monitoring systems;
- **Demonstration** of the system **in several cities**; [...]



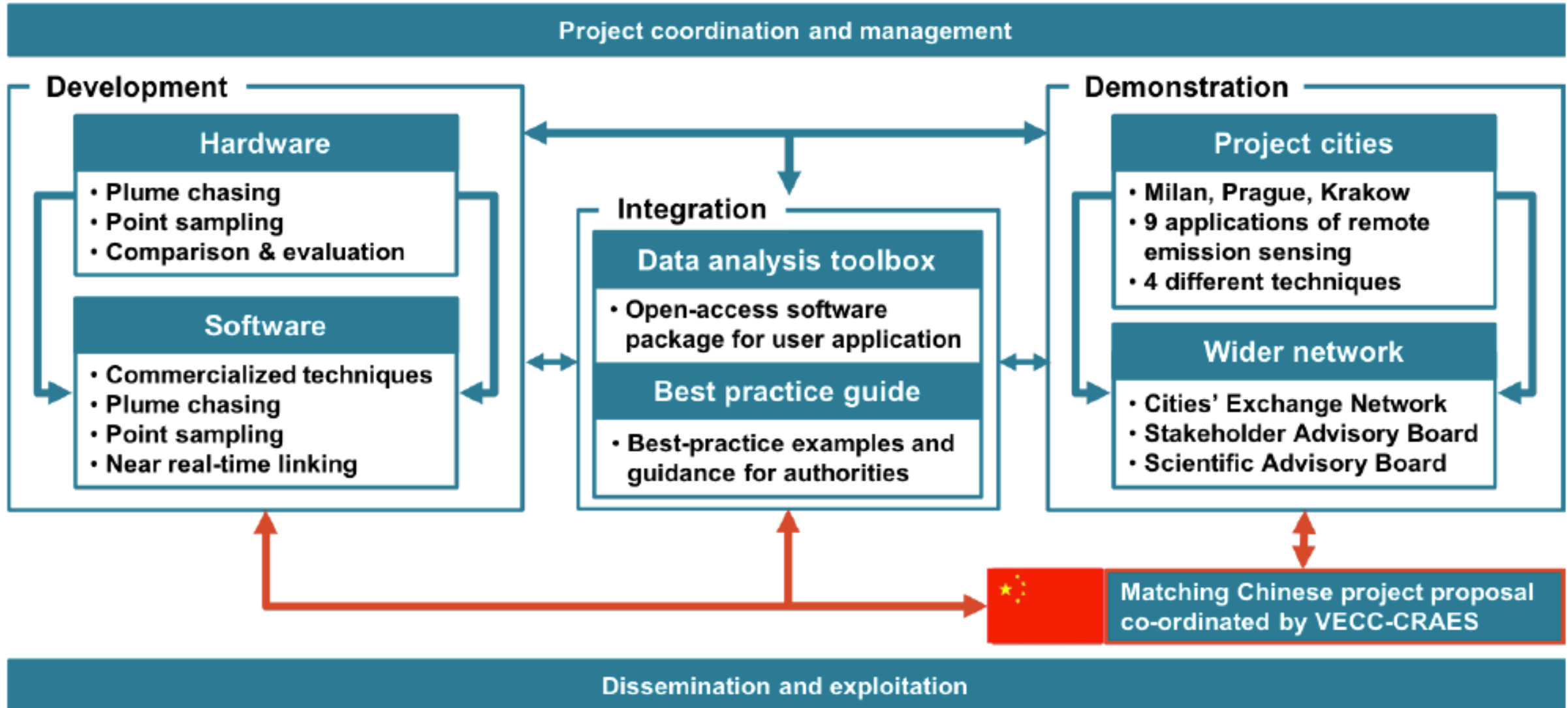
What is CARES?

Bringing together remote sensing experts



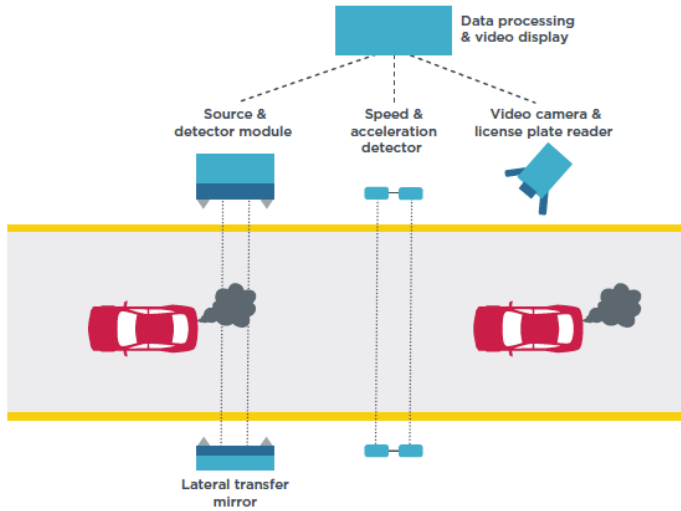
What is CARES?

Overall project structure

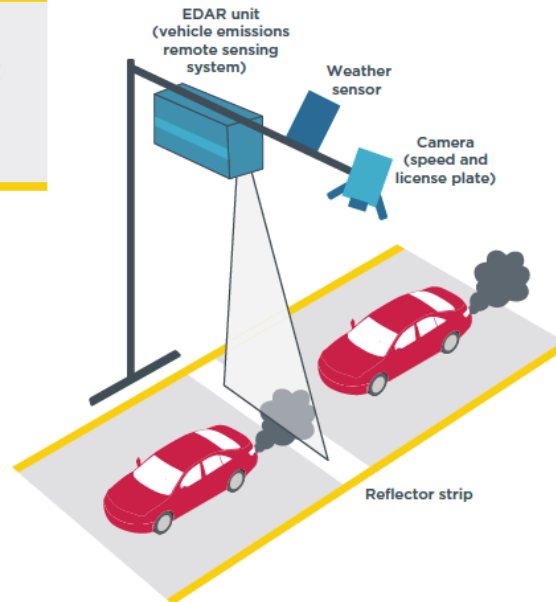


Working package #1

Hardware development



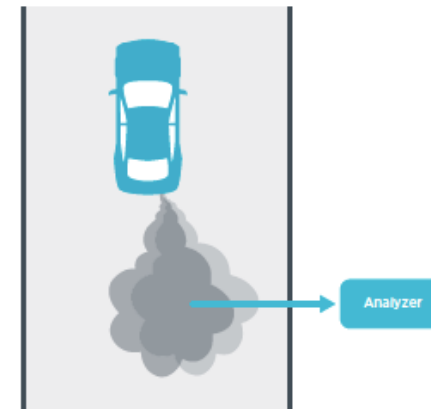
Schematic of cross-road remote emission sensing device.



Schematic of top-down remote emission sensing device.



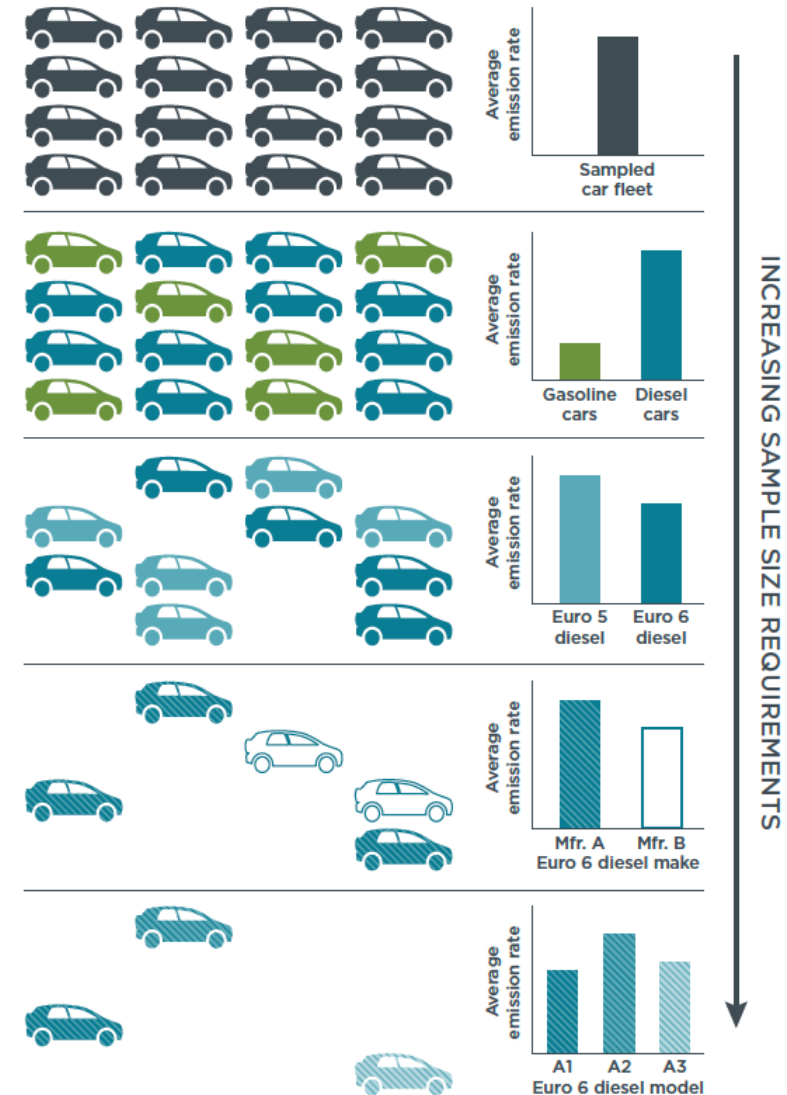
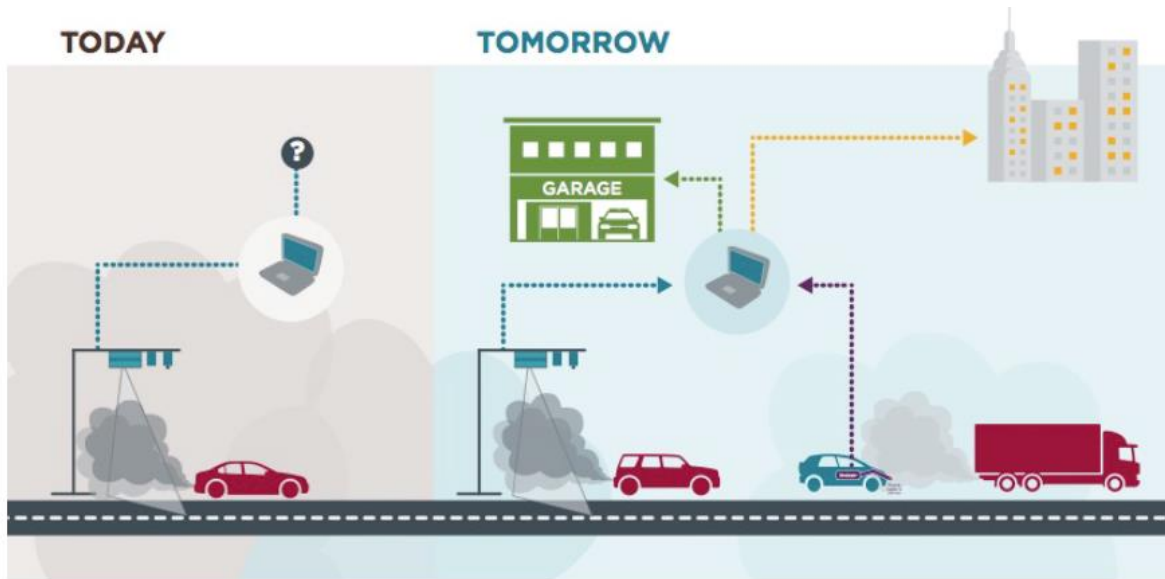
Schematic of plume chasing remote emission sensing device.



Schematic setup of point sampling remote emission sensing device.

Working package #2

Software development



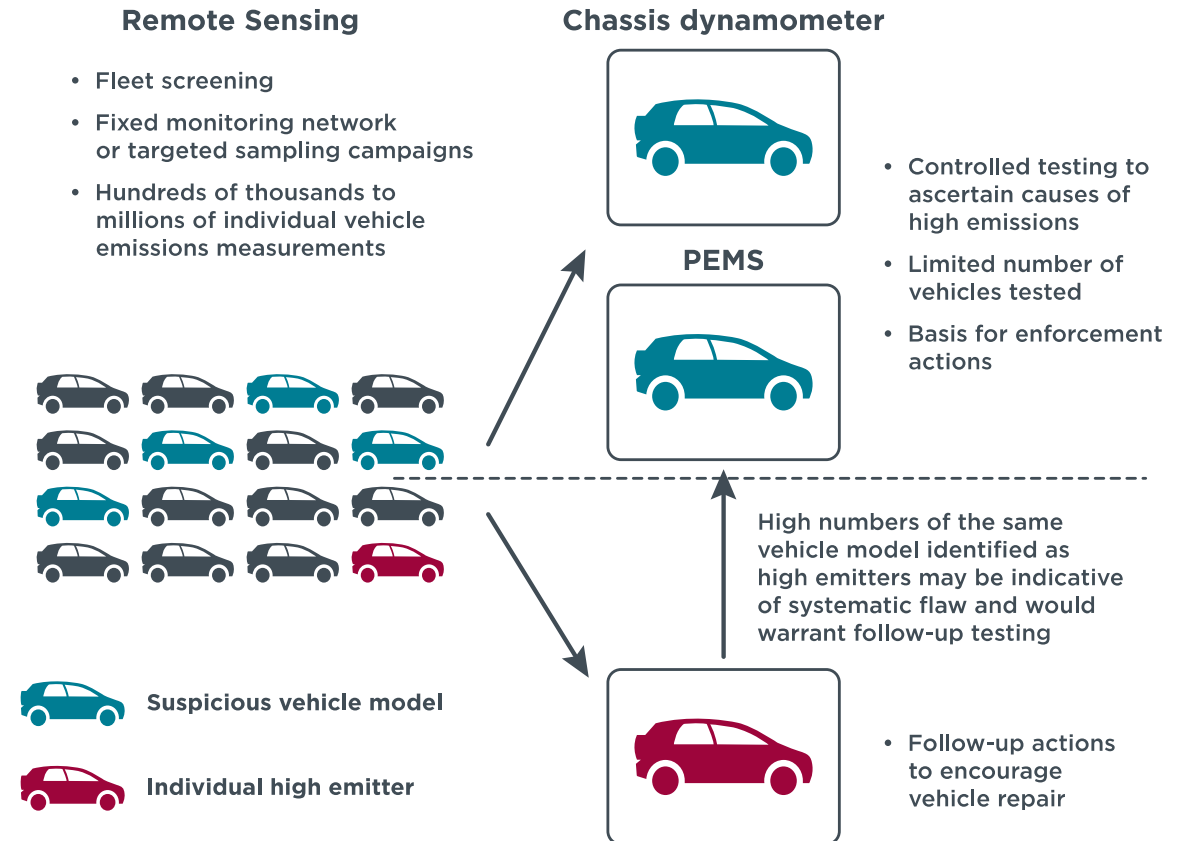
Potential applications of remote emission sensing

- 1) Identification of individual **high (or low) emitters**
- 2) Generation of real-world **emissions factors**
- 3) Steering **new policies**
- 4) Tracking **policy effectiveness**
- 5) Track **technology effectiveness**
- 6) Screen fleet for **market surveillance**
- 7) Monitor a **single fleet**
- 8) Understand the **impact** of specific driving and ambient conditions
- 9) Inform **purchasing decisions**

Working package #3

Planned city demonstrations

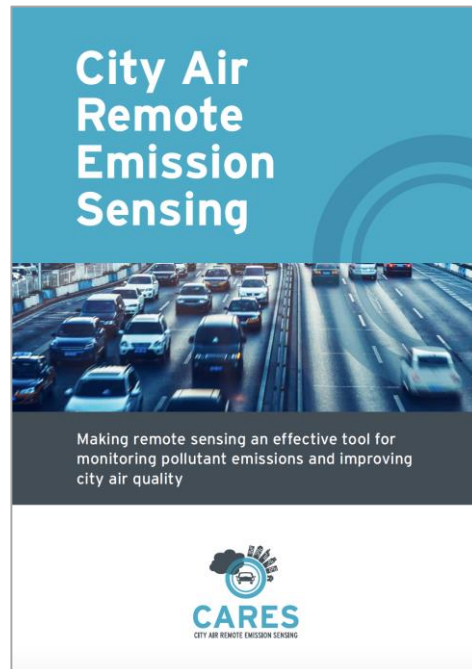
- **Prague**
Identification of individual high emitters
- **Milan**
Track policy effectiveness
- **Krakow**
Steer new policies



Working package #3

Knowledge exchange

- Between **cities**
- Including **member states** and **stakeholders**
- With our **Chinese partners**



<https://cares-project.eu>



WP1 – Further developing plume chasing and point sampling techniques

David Carslaw and Naomi Farren University of York

Denis Pöhler, Christina Schmidt, Stefan Schmitt Airyx GmbH

Markus Knoll, Alex Bergmann Graz University of Technology

Norbert Ligterink, Paul Tilanus, Gerrit Kadijk TNO

Karl Ropkins University of Leeds

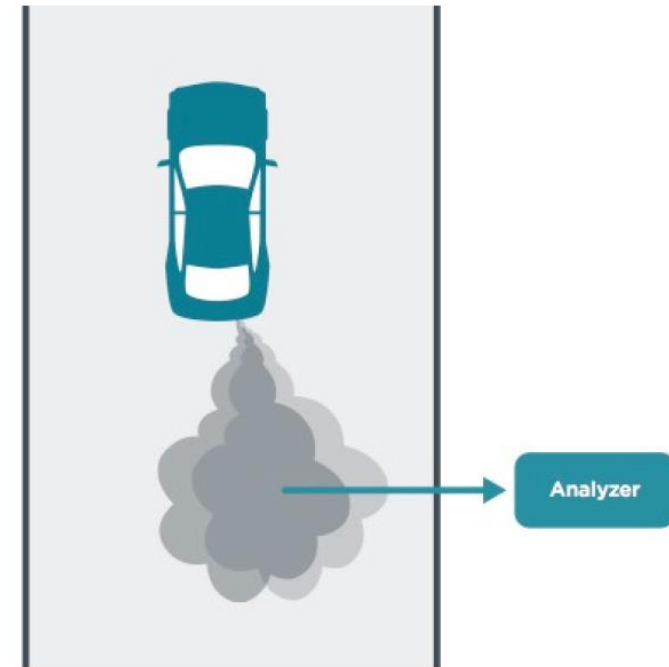
Åsa Hallquist IVL

1st Stakeholder Advisory Board Meeting



WP1 – Further developing plume chasing and point sampling techniques

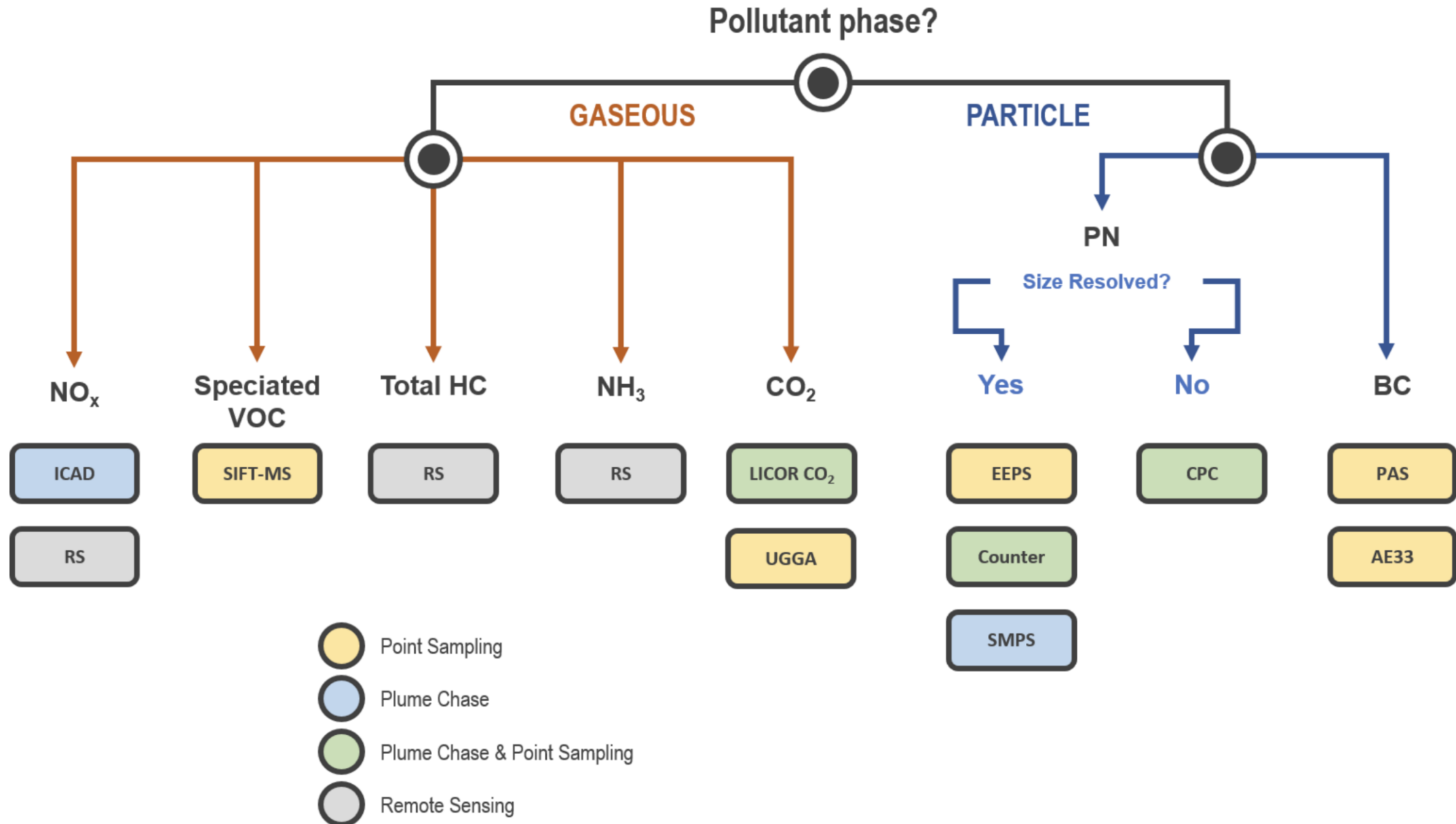
- Brings together a range of **remote emission sensing** (RES) techniques
- Focus is on hardware development
 - Plume chase
 - Point sampling
 - [Remote sensing] Already commercially available



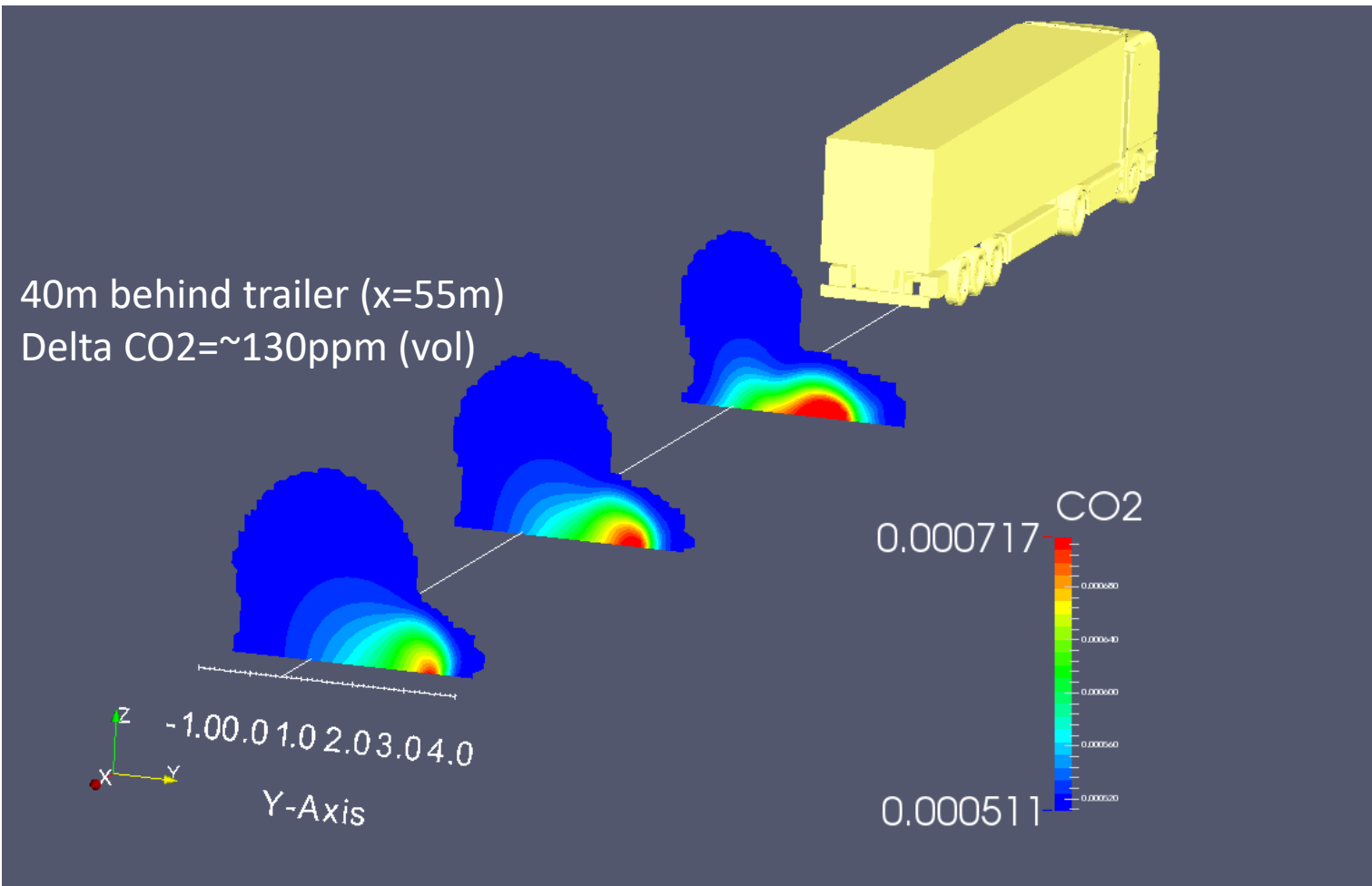
WP1 – Brief summary of main tasks

- Task 1.1
 - Hardware development for **plume chasing** (**Airyx**, UoL, TNO)
- Task 1.2
 - Hardware development for **point sampling** (**TUG**, IVL, UoY)
- Task 1.3
 - Controlled **characterization experiments** (**TNO**, IVL, UoY, UoL, TUG) **Tentatively postponed until end October 2020**
- Task 1.4
 - Technology **hardware evaluation** (IVL, UoL, **UoY**, TUG, UoH, ICCT, IIASA)

WP1 – Measurement overview



Plume chase – CFD modelling (TNO)



- Where best to measure for plume chase vehicles?
- Hope to complement with visible plume tests during characterisation testing

Plume chase – Sniffer vehicle set up

Inlet positions and instruments:

CPC/SMPS/CPC
(particles)

PN Prototype

camera

Background CO₂
Background NO_x

Inlet2:
ICAD 2 (NO_x, CO₂)
LI-COR 2 (CO₂)

radar

Inlet1_2

Inlet1:
ICAD 1 (NO_x, CO₂)
LI-COR 1 (CO₂)

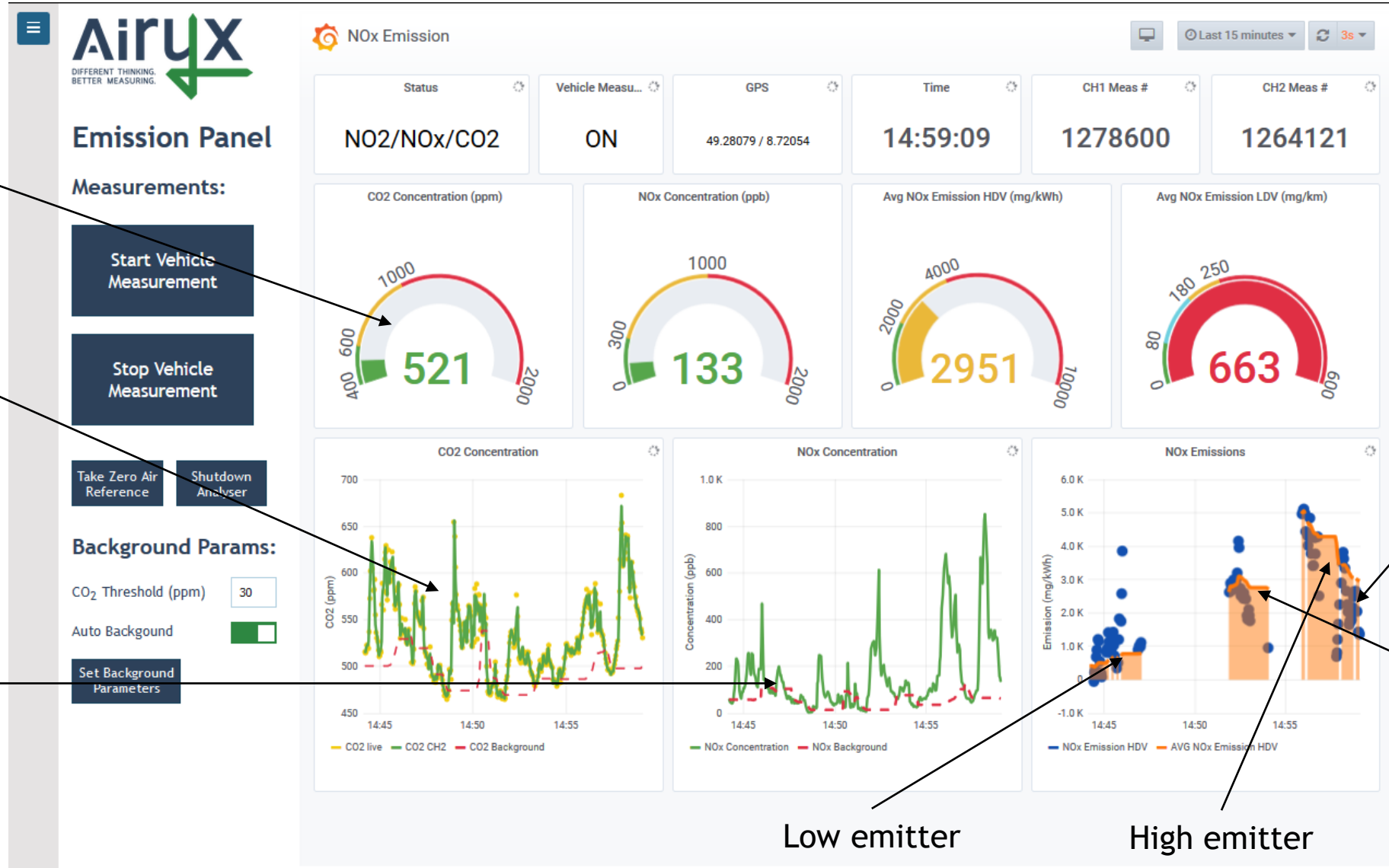


Plume chase – Live information

Current CO₂ conc. →
plume signal strength

Time series CO₂ conc. &
estimated CO₂ background

Time series NO_x conc. &
estimated NO_x background



Time series NO_x Emission factors:

instantaneous (blue)

Average since „Start“ (orange)
→ one result per vehicle saved in extra file

Point sampling

- Photoacoustic Sensor Development (black carbon + other components)
- Diffusion Charging (particle number)
- Other instruments to help evaluation

Photoacoustic Spectroscopy



$$S(\lambda) = F \cdot \alpha(\lambda) \cdot P_0(\lambda) \quad [1]$$

S ...photoacoustic signal

F ...properties of the applied environment (cell constant)

α ...absorption coefficient of the analyte

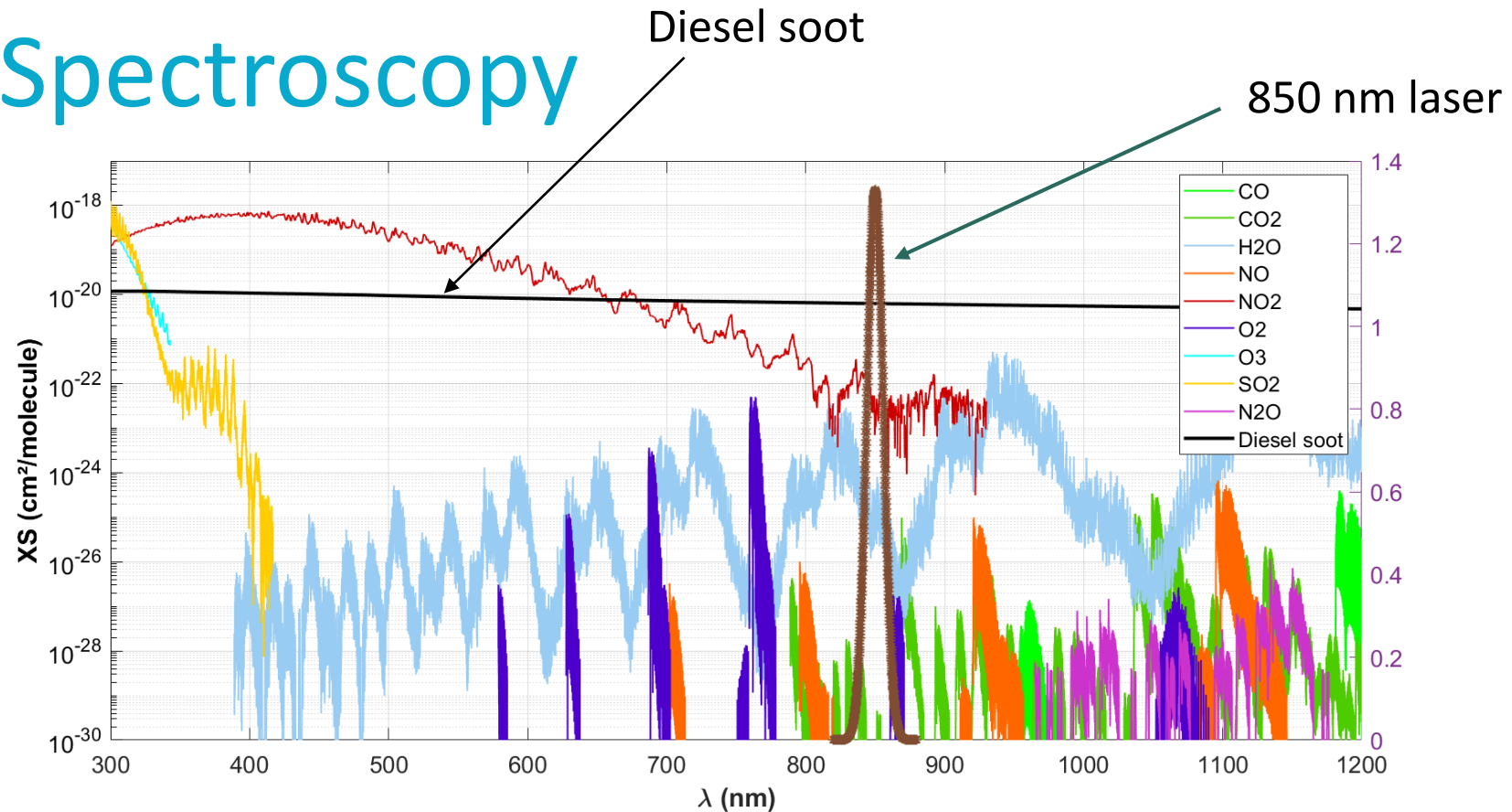
P_0 ...optical power of the light source

[1] Christoph Haisch. "Photoacoustic spectroscopy for analytical measurements.

"In: Measurement Science and Technology 23 (1 2012). doi: 10.1088/0957-0233/23/1/012001.

Photoacoustic Spectroscopy

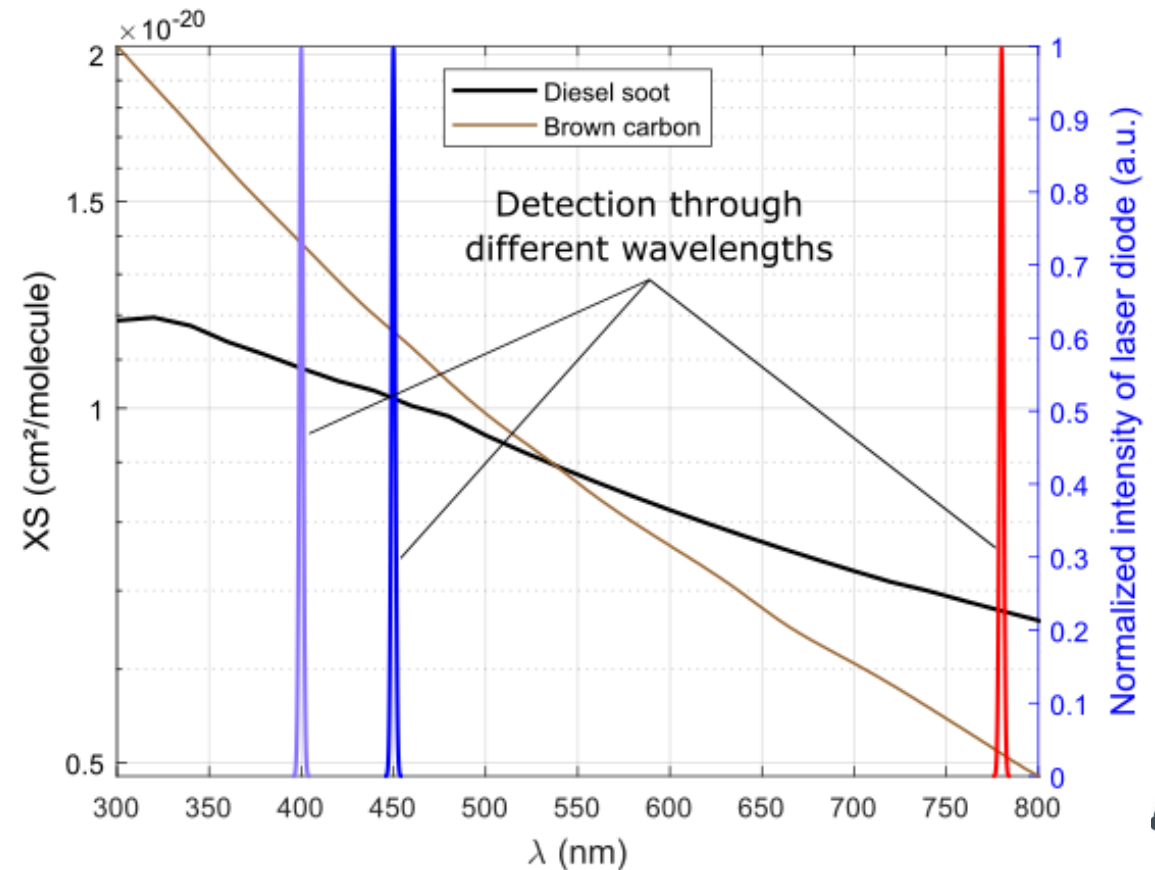
- Soot: Broadband absorber
→ absorption coefficient decreases with increasing wavelength
- Selection of proper wavelength → No interference with other particles / gases
- E.g. 850 nm proper choice to avoid interference with O_3 , SO_2 , CO_2 , CO , ...



Source Appointment

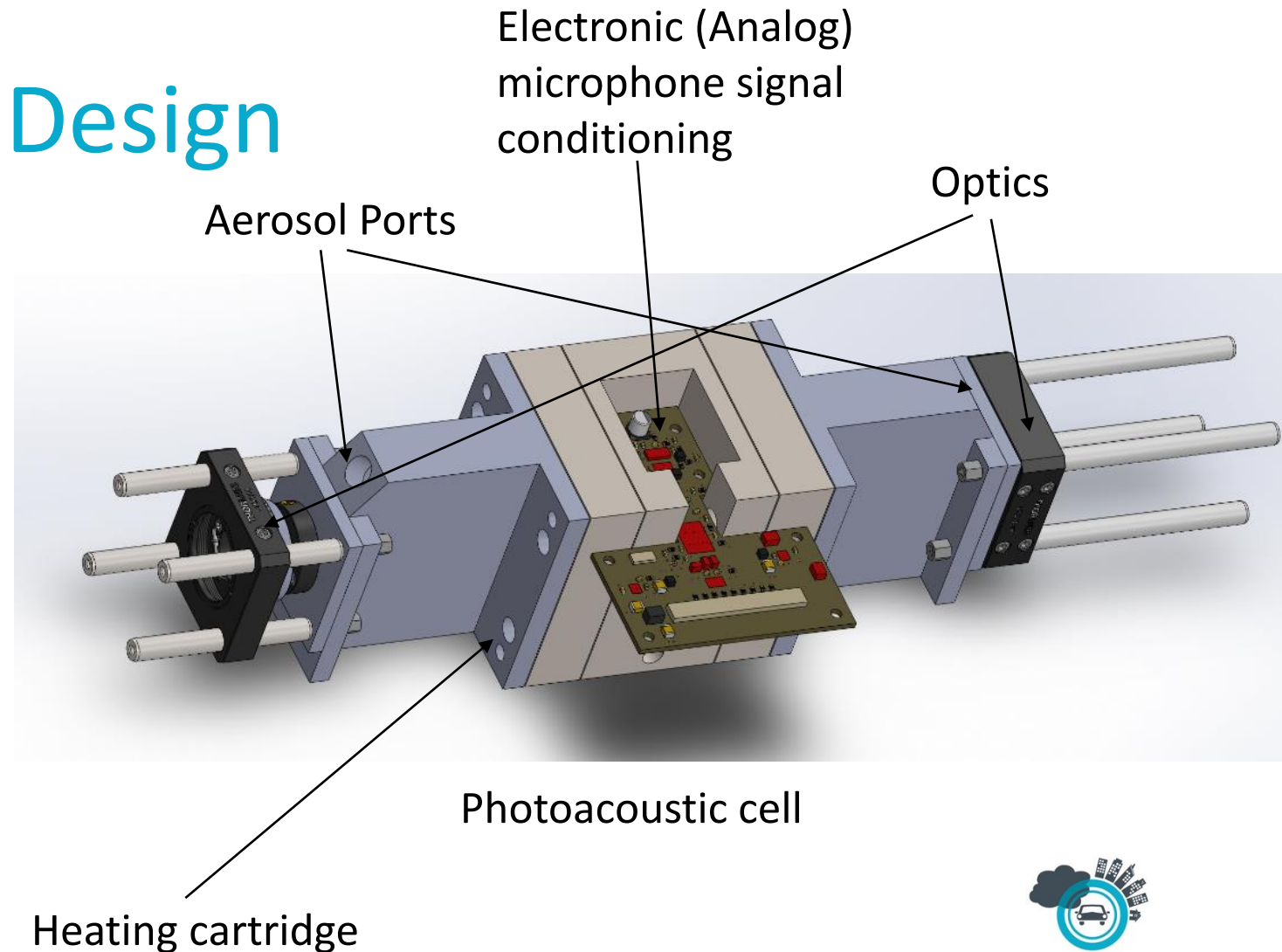
- Source Appointment → Are the measured particles vehicle combustion based?
- Detection of black carbon (soot)
 - Faults of exhaust after-treatment system
 - Faulty diesel particulate filter
- Distinction of different pollutants with a multi-wavelength approach. Distinction between automotive exhaust and other sources (for example domestic fuel burning)
 - Black carbon
 - Brown carbon
 - Tyre, break particles ...

Absorption cross section of Diesel soot, brown carbon and normalized intensities of light sources



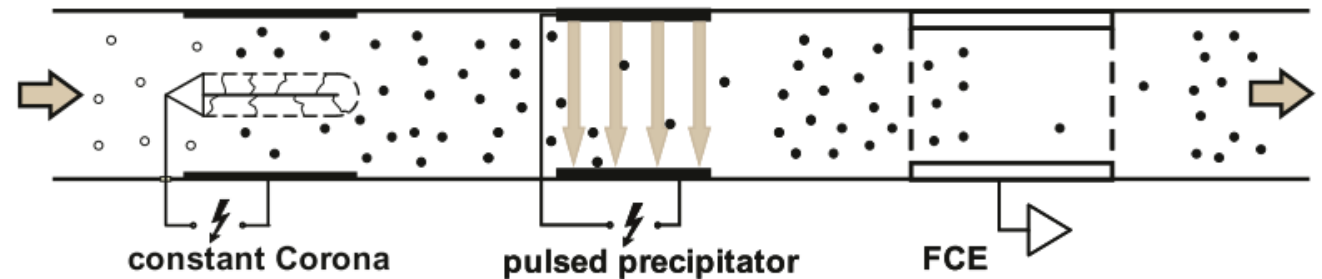
Photoacoustic Cell Design

- Second generation cell design
- Analog signal conditioning is directly at the sensor performed
- Heating cartridges for temperature stabilization
- Optics directly attached to the cell
- External components
 - Mainboard (Flow control, temperature stabilization, Signal processing, Data handling)
 - Laser driver



Diffusion Charging

- **Particle number measurement**
- Principle: Electrical charging of particles and subsequently measurement of the resulting current
- Sensor response can be correlated with PN → Pulsed Mode Diffusion Charger (PMDC)
- Measurement range appropriate for detection of exhaust after-treatment failures related to particles (DPF, ...) → $10^3 - 10^7$ particles / cm³

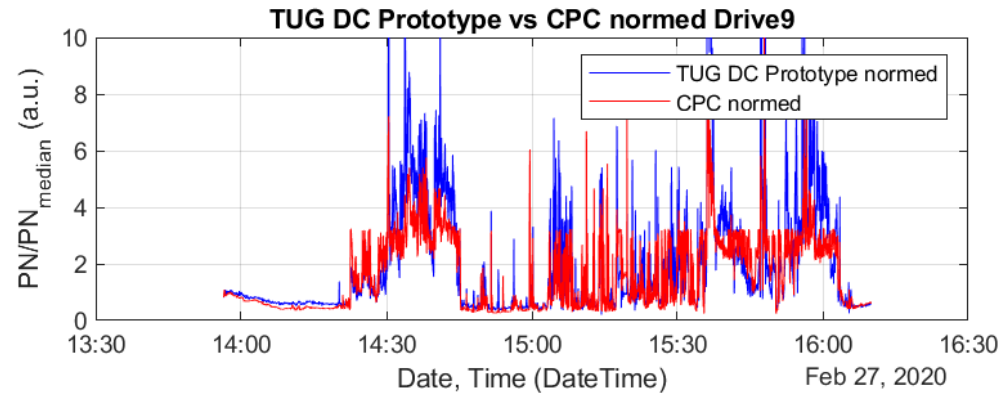
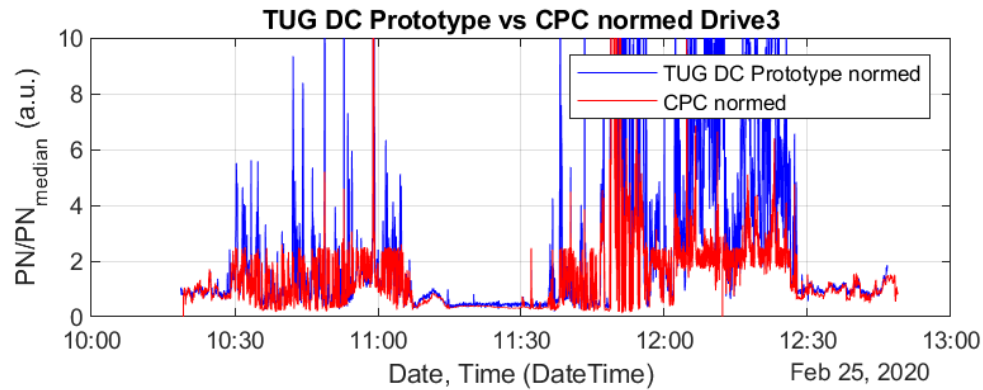
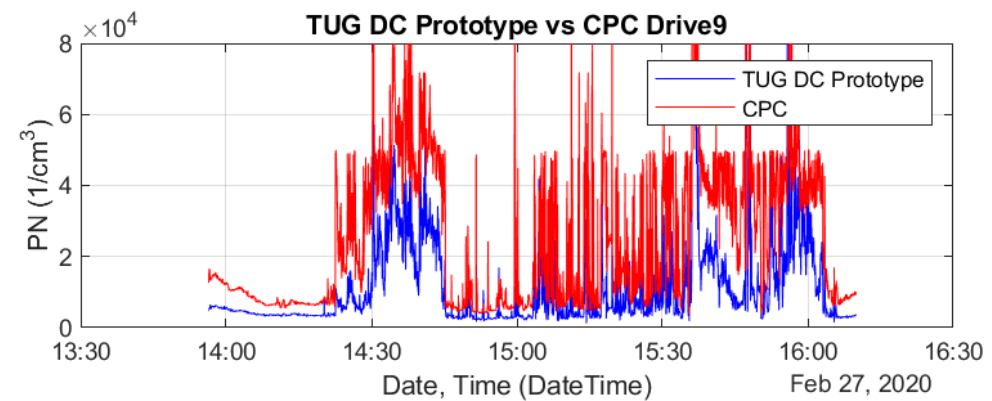
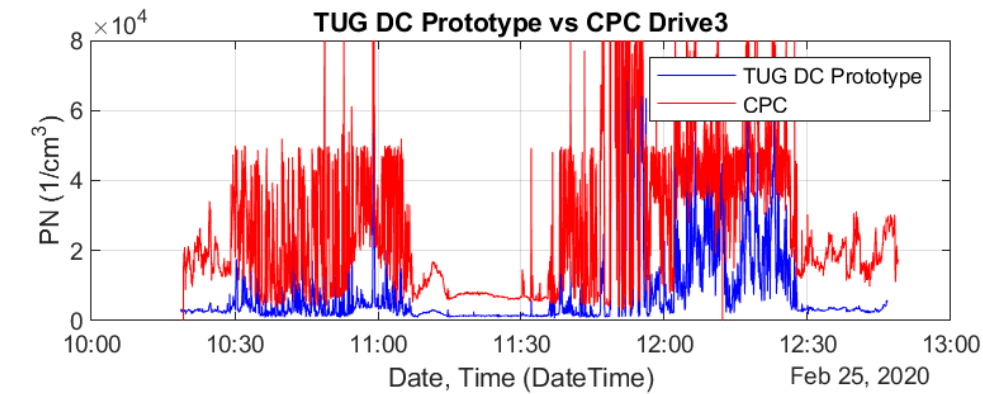


[2] Schriebl A., Bergmann A., Fierz M. . Design Principles for Sensing Particle Number Concentration and Mean Particle Size With Unipolar Diffusion Charging. IEEE Sensors Journal. 2019.

[3] Schriebl M.A., Nishida R.T., Knoll M., Boies A.M., Bergmann A. . Characterization of Particle Number Counters Based on Pulsed-Mode Diffusion Charging. Aerosol Science and Technology. 2020.

- Used in plume chase experiments

Diffusion Charging – Plume Chase Experiments





CARES
CITY AIR REMOTE EMISSION SENSING

WP2: Standardizing remote sensing data management processes

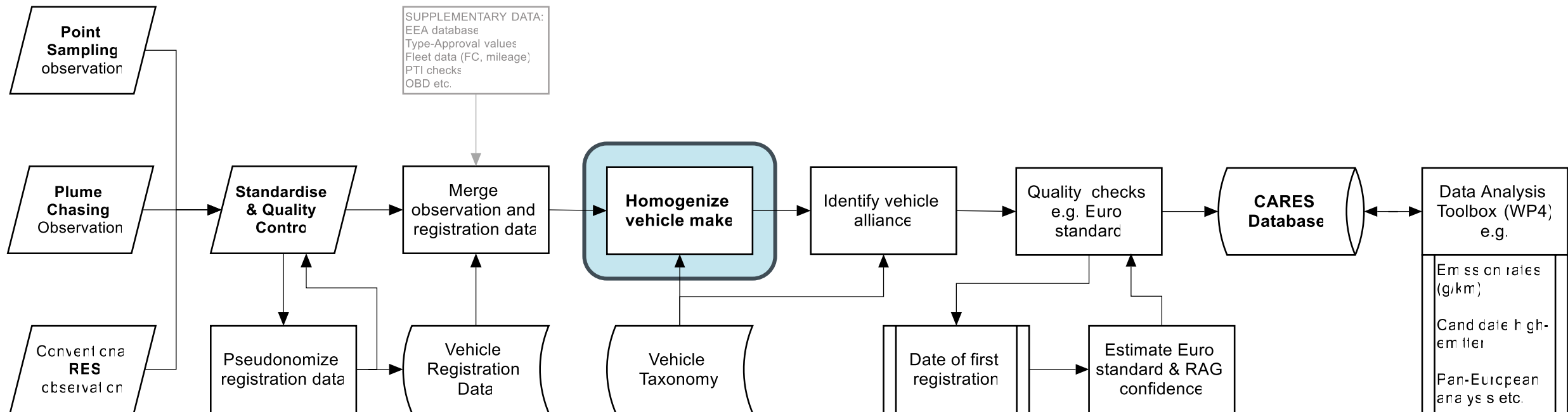
*Maximizing the potential of remote
sensing observations*



Work Package #2

Software development

- Supporting more efficient and standardized (robust) RES data handling
- Organise, analyse, enrich and link different types of RES data
- Make RES data accessible to enforcement agencies, cities & scientists



Work Package #2

MSCW Prioritization Approach for Database Entries



CARES
CITY AIR REMOTE EMISSION SENSING

Conventional Remote Emission Sensing, Plume Chasing and Point Sampling measurements will all be entered into the CARES database following a standard form. The requirements for the CARES database entries are prioritized using a *MoSCoW* approach:

EXAMPLES:

M

Must have: Non-negotiable requirements that are mandatory for further work to proceed.

- Emissions measurement
- Anonymized vehicle specifications

S

Should have: Important includes that, whilst not vital, add significant value.

- Pseudonomized License Plate Data
- Meteorological Data

C

Could have: Nice to include to enhance data, but may only have small impact if not available

- Country of Origin
- Emissions After-treatment System Data

W

Will not have: Not a priority at this time. May return to these later in the project or as future work.

- Vehicle Color
- License Plate record

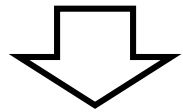
Work Package #2

Software development

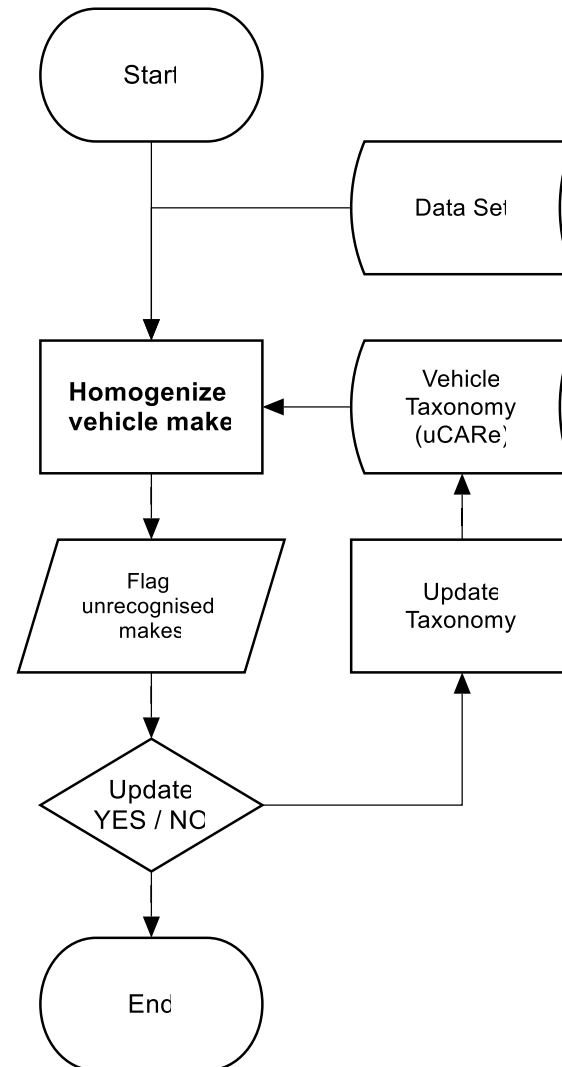
*Homogenize vehicle make:
Example Swiss (CH) data
from the 2018 and 2019
campaigns*

e.g.

Daimlerchrysler AG
Mercedes
Mercedes-AMG
Mercedes-Benz



Mercedes



Switzerland Passenger Car Data

2018

2019

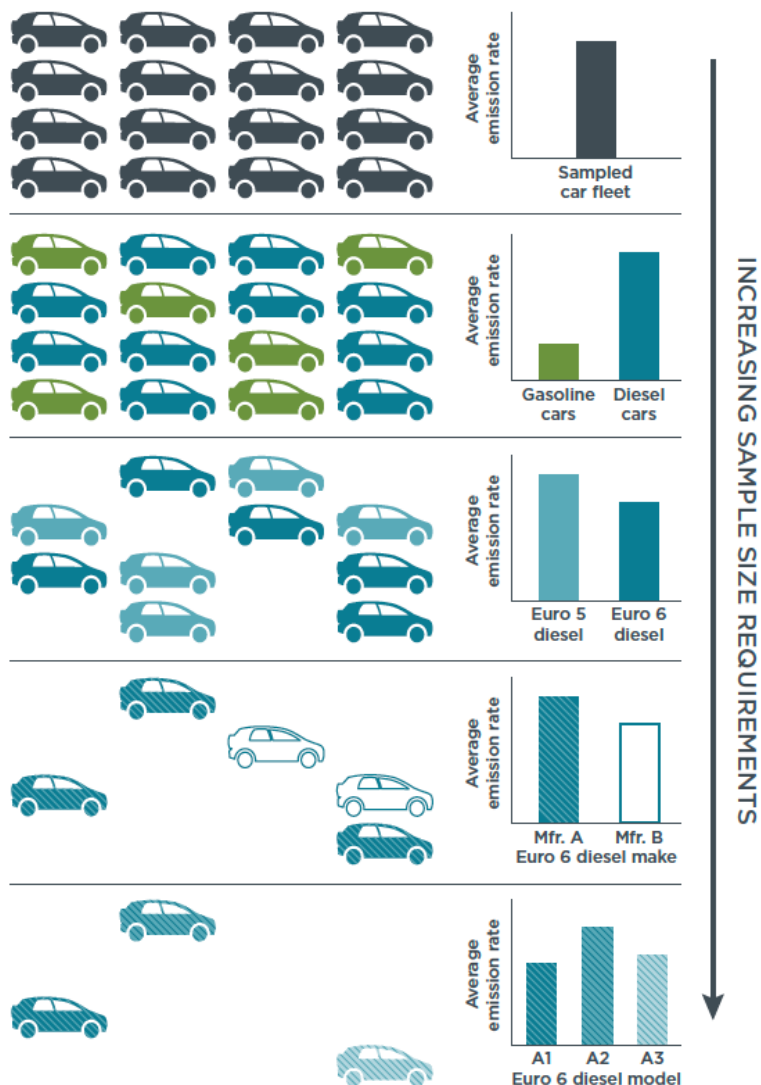
71622 records
4.2% flagged
10 unrecognized makes
9 new makes identified
Alfa, Mini UK, Smart,
Fortwo, MG, Quattro,
Mercedes-AMG, Buick,
Pontiac
1 unidentified / others
Ovriga*

69349 records
0.2% flagged
3 unrecognized makes
2 new makes identified
Triumph, Hummer
1 unidentified / others
Ovriga*

*Ovriga translates to 'Others' in Swedish.

Work Package #2 and #4

Software development >> Data Analysis Toolbox



- Distance-Based Emission Factors (grams.km⁻¹) from Vehicle Emission Remote Sensing Measurements ¹
- Identify candidate high-emitters
- Calculation of minimum sample sizes ²
- Pan-European analysis ³

¹ Davison, J., Bernard, Y., Borken-Kleefeld, J., Farren, N., Hausberger, S., Sjödin, Å., Tate, J., Vaughan, A., Carslaw, D. 2020. Distance-Based Emission Factors from Vehicle Emission Remote Sensing Measurements. Science of the Total Environment. Accepted publication May 2020.

² Chen, Y., Zhang, Y., Borken-Kleefeld, J. 2019. When is Enough? Minimum Sample Sizes for On-Road Measurements of Car Emissions. Environ. Vol 53, 22, pp13284–13292, DOI: 10.1021/acs.est.9b0412

³ Sjödin, Å., Borken-Kleefeld, J., Carslaw, D., Tate, J., Alt, G.-M., De la Fuente, J., Bernard, Y., Tietge, U., McClintock, P., Gentala, T., Vescio, N., Hausberger, S. (2018), Real-driving emissions from diesel passenger cars measured by remote sensing and as compared with PEMS and chassis dynamometer measurements- CONOX Task 2 report, Commissioned by the federal Office for the Environment (FOEN), Switzerland, IVL C294

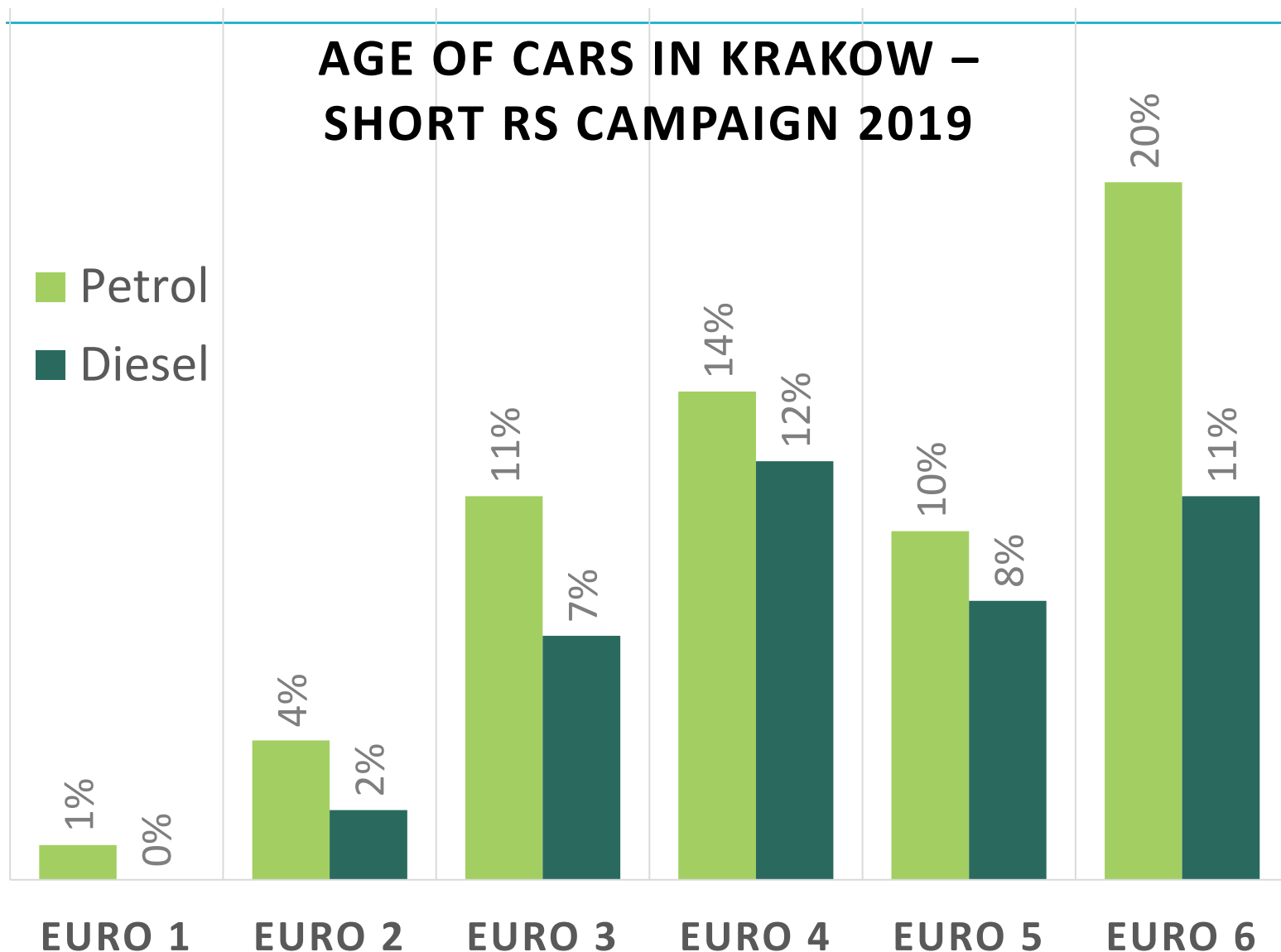
Monitoring of in-use vehicle emissions – helping their enforcement (Work package #4)

All developments to measure vehicle emissions quickly, reliably, representatively => Monitor & help enforce in-use emissions!

Applications by partner (cities) concerned with high vehicular pollution:

- 1) Determine real-world **emissions**
- 2) Informing **policies**
- 3) Tracking **policy effectiveness**
- 4) Screen for **market surveillance (model) & Screen fleet for high emitter detection (individual vehicle)**

Krakow: RS campaign Oct 2019 – informing the situation



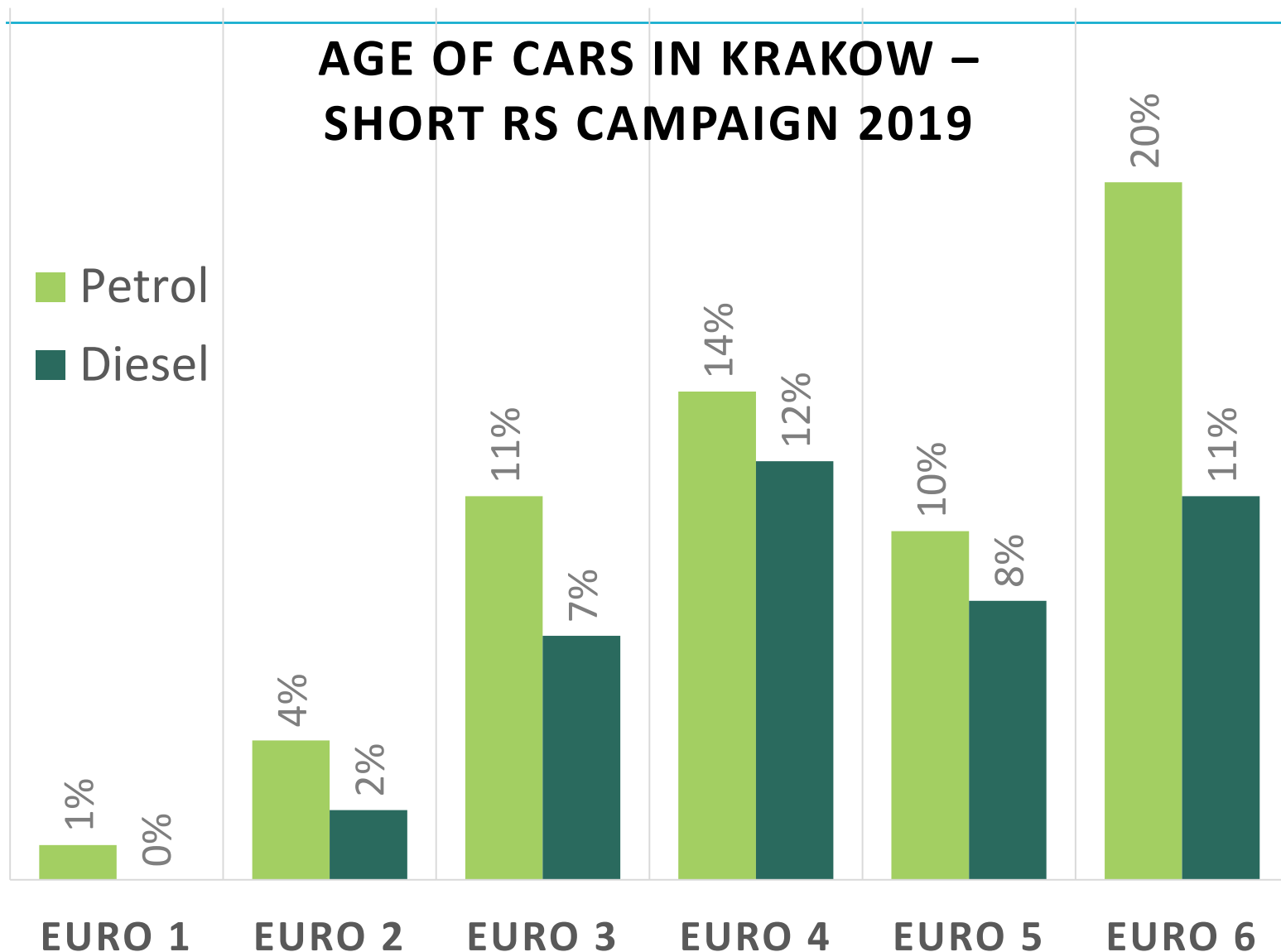
Petrol:

16% Euro 3 or older
(15 years+)

Diesel:

29% Euro 5 or older
(5 years+)

Krakow: RS campaign Oct 2019 – informing the situation



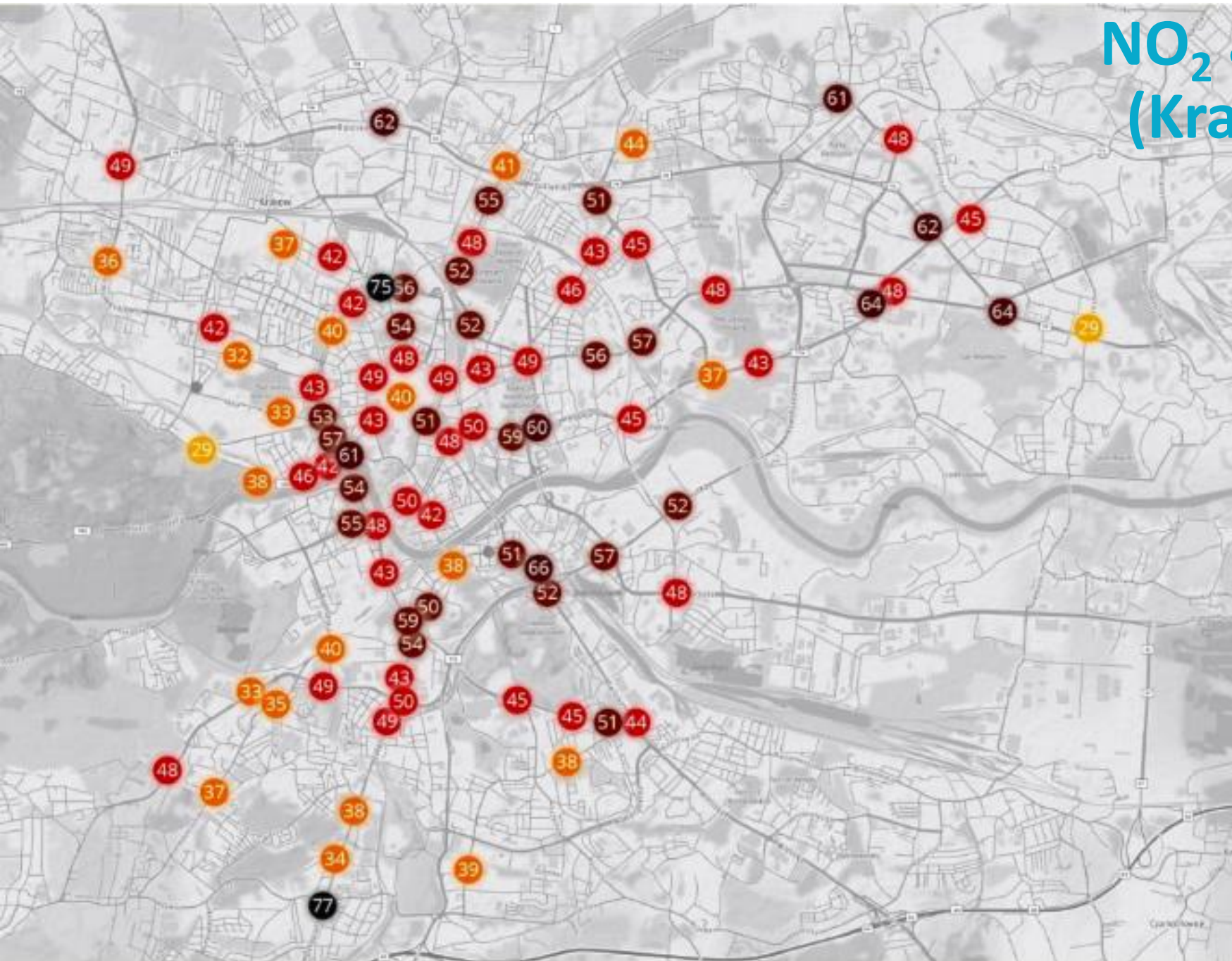
Petrol:

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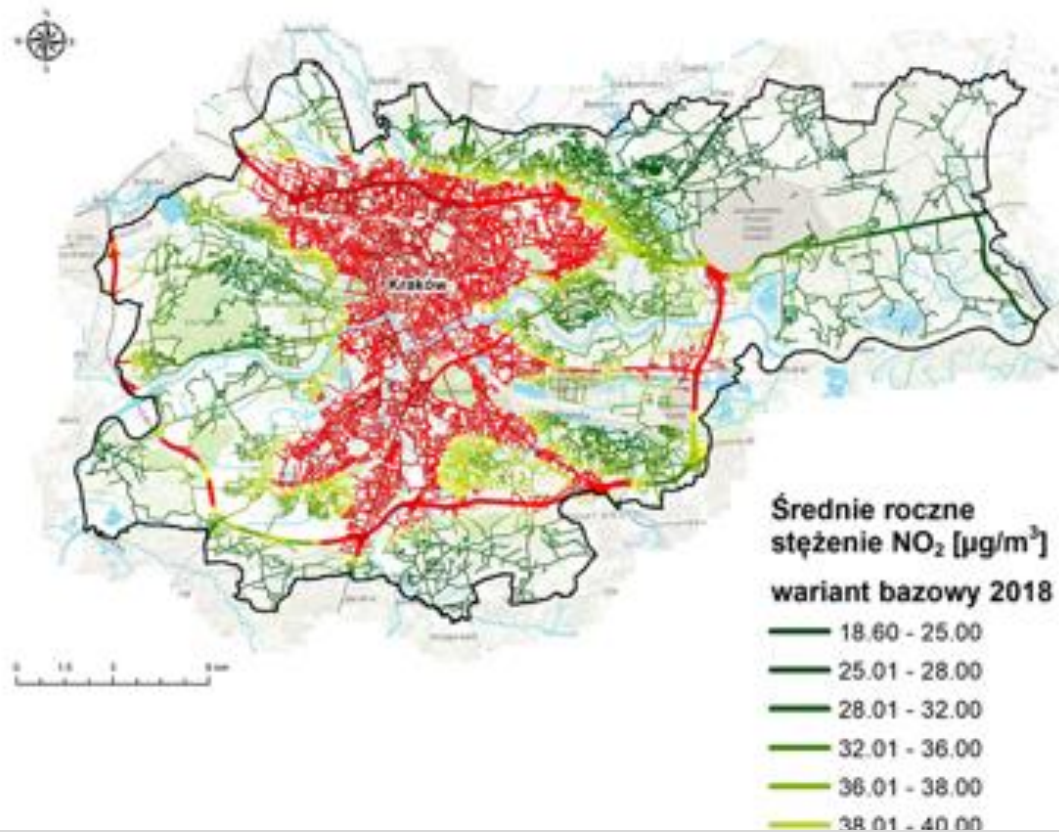
NO₂ ambient samples (Krakow - Nov. 2019)



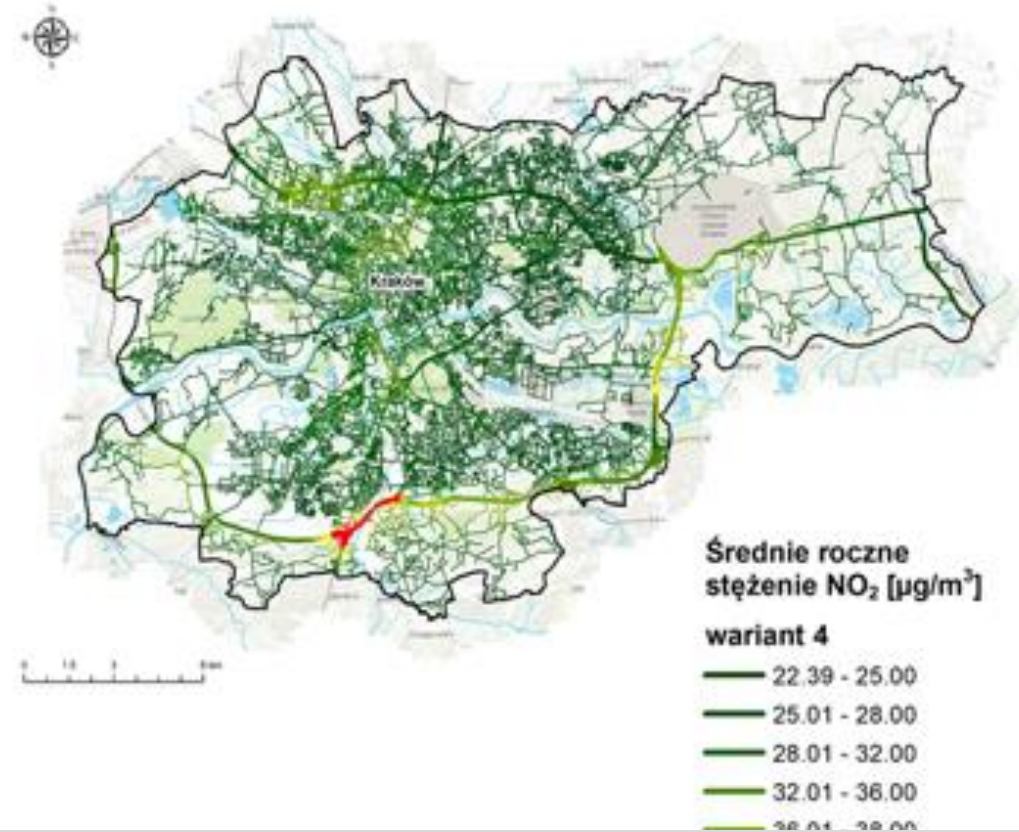
**Inner city between
40 – 60 μg/m³ NO₂**

2020 Air Quality Program – LEZ proposal

NO₂ concentrations – base year 2018



NO₂ concentrations – LEZ proposal:
EURO 4 for petrol and EURO 6 for diesel



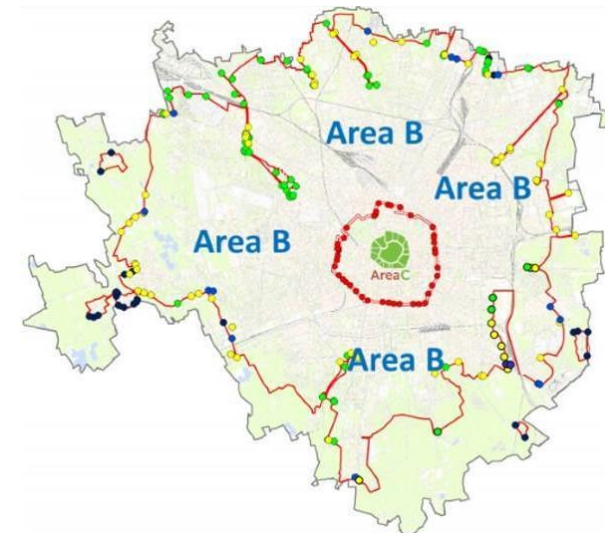
RS measurements to better inform –
and test possibilities for monitoring & enforcement

City of Milan – Innovhub SSI & AMAT



Milan: Persistent exceedances of PM and NO₂ AQ limits.
LEZ for center (AREA C, 8 km²) and AREA B, 128 km² ⇔
No diesel vehicle up to EURO 4. Guarded by electronic gates.

Will NO₂ problem be solved with presumably clean Euro 6 vehicles?
(Track policy effectiveness). Ideally, also detect NH₃, soot, PM/PN!?



RES campaign

Top-down RS & point samplers deployed at 2 spots in city aiming for ~100,000 vehicle emission records.

Add-on partner components: PEMS validation tests and possibly air quality monitoring

Endorsement and availability of **Ministry of Transport** to share vehicles registration and PTI data.

Cooperation with the **Municipality of Milan**

(AMAT is developing the Municipality Air Quality and Climate Plan)



Milan campaign open points (in progress)



INNOVHUB
STAZIONI SPERIMENTALI
PER L'INDUSTRIA

innovazione e ricerca

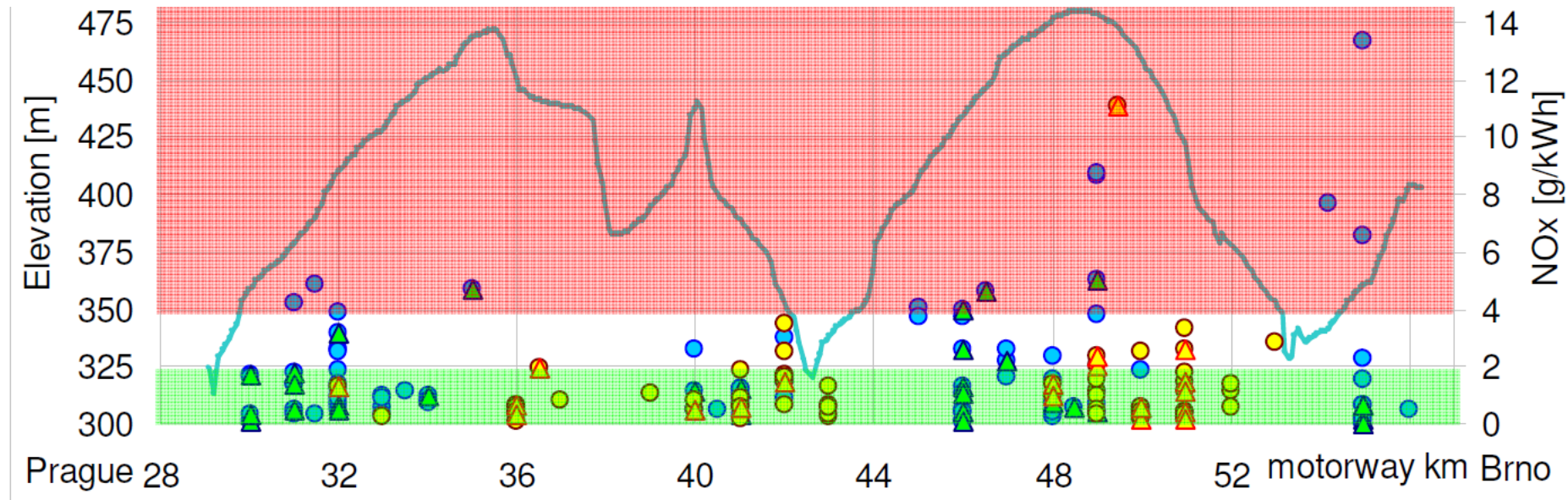


- Keen interest in PM and PN measurements. Accuracy?
- Ammonia (NH_3) emissions significant. Instrument available?
- Can point samplers be deployed at sites from the center to the limit of the city?
- Can they discriminate emission rate from single vehicle over a two or more lanes road?
- Set-up: Deploy top-down (EDAR) RS instrument and point sampler at
 - a one lane road;
 - a two lanes road next to an Area B (or Area C) electronic gate.
- Maybe also plume chasing validation? Following one high emitter with a PEMS on board, to compare with plume chase vehicle emissions?



Prague: Focus on high-emitter detection

- Understanding fleet and identifying contribution from high-emitting vehicles
 - Heavy-duty vehicles \Leftrightarrow plume chase vehicles
 - Cars (taxis), buses \Leftrightarrow cross-road remote sensing
- Done: some probing campaigns on PM roadside and highway plume chase
- Cooperation with Customs Office, Ministry for Environment, City of Prague



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- 2) Informing **policies**

Your views, questions, experiences?

- 3) Tracking **policy effectiveness**
- 4) Screen for **market surveillance (model) & Screen fleet for high emitter detection (individual vehicle)**



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CONSORTIUM PARTNERS



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HEIDELBERG
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